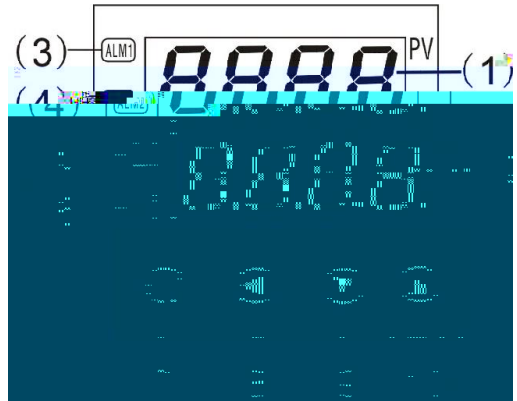




PV
 SV
 ALM1
 4 ALM2
 5 A-T
 6 OUT
 7 SET 3
 8
 9
 10



4-1

0	SP		P-SL P-SH	run=0 " "	50

1	ALI		P-SL P-SH	"ALP" 0.5 5	200
2	AL2		0-200		0
3	Pb		±20.0		0.0
4	P		1 5000	KP P=0 4-1	100
5	I		0 3000	I	500
6	d		0 2000	D " " 0 " "	100
7			2 120	PID 10	10
8	FLt		0 50		20
9	HY		0.1 50.0		0.5
10	dP		0 3	0 1 0 3 dp=0 0000 dp=1 000.0 dp=2 00.00 dp=3 0.000	1
11	outH		outL 200		200
12	outL		0 outH		0
13	At		0 1	0 1 " "	0
14	LoCt		0 50	0 1	0
15	Sn		—	4-2	2
16	oP-A		0 7	0 1 2 5 0 10mA 0 5V 6	

				3. 4-20mA	
22	Addr		0 255	" " " "	1
23	bAud		—	'0'1200 '1'2400 '2'4800 '3'9600	9600
25	SEC		0 1	0 1	0
26	Loop		0 1	0 1	1
27	PdE		0 3	0 1 1 2 3 1	0
28	AL-P		0 100.0	AL_P, pv-sv >AL_P	10
29	run		0 3	'0' SP '1' '2' '3' "7-2"	0
30	Pro		0 64		1
31	tE			RS485	
32	rDI	1	0-2000	0 run=1 pro=1 2000	10
33	rDI	1	0 9999	1 , 0	10
34	COI	1	P-SL P-SH	1 1 SPx, SP1	50
125	r32	32			
126	r32	32			
127	r32	32		32 32 SP32	

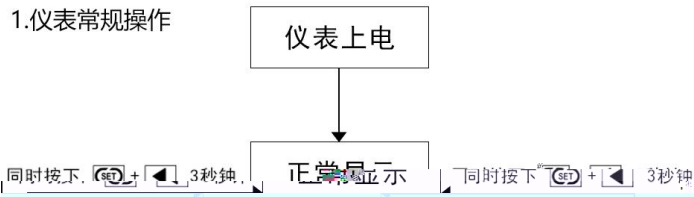
4-2

	Cu50(50)	Pt100(1)	Pt100(3)
	-50.0 150.0	-199.9 200.0	-199.9 600.0
	K(5) -30.0 1300	E(5) -30.0 700.0	J(5) -30.0 900.0
	T(5) -199.9 400.0	S(5) -30 1600	R(5) -30.0 1700.0

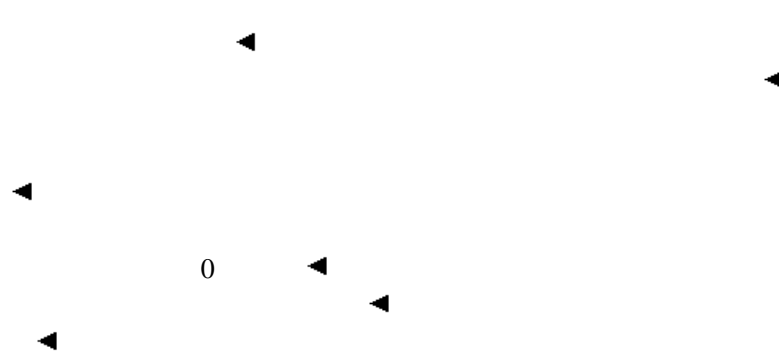
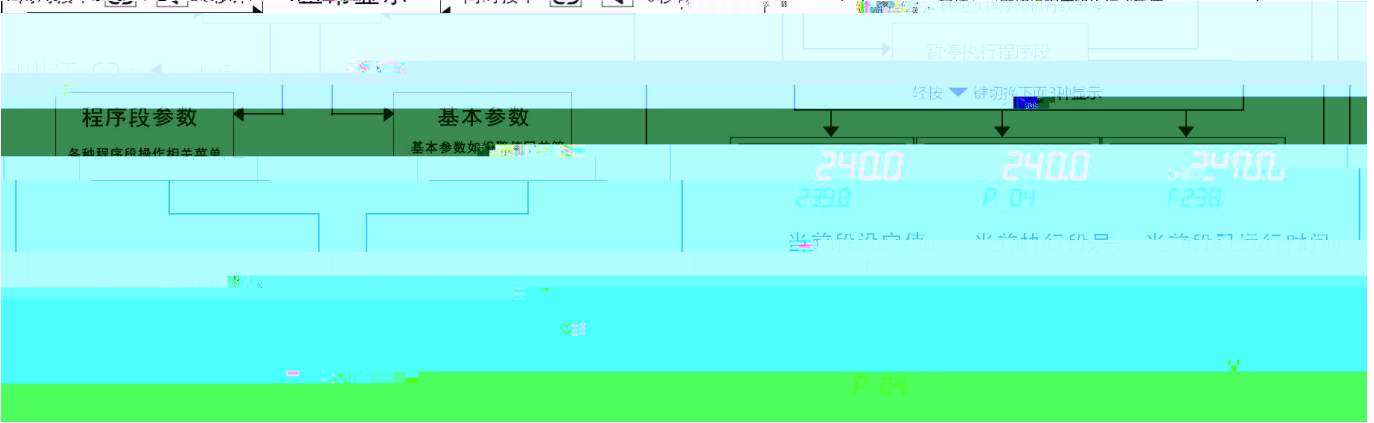
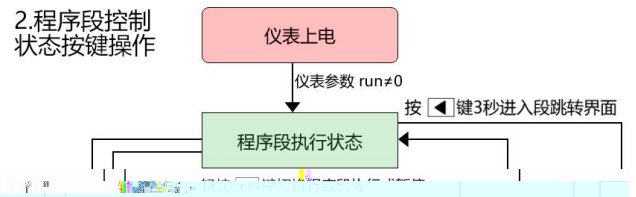
4-3

	KP=0; COOL=0; KP=0; COOL	=SP+HY	=SP-HY
--	-----------------------------	--------	--------

1. 仪表常规操作



2. 程序段控制
状态按键操作



D

1.

K

2.

10%
"AT"

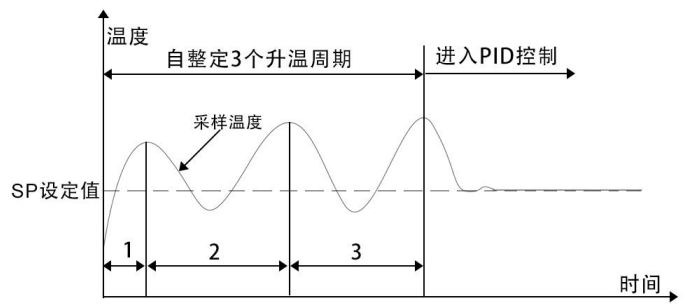
1

AT

"SP"

0.5
SV

P I



“AT” P I D , ,AT , “AT” 0 PID



- 1. REST
- 2. REST

- 3.
- 4.

LOOP=1

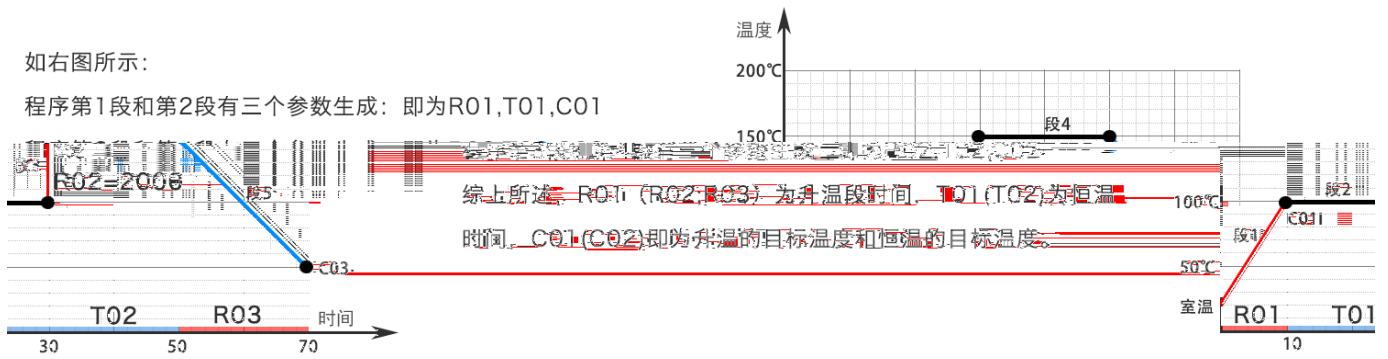
LOOP=0

- 5.

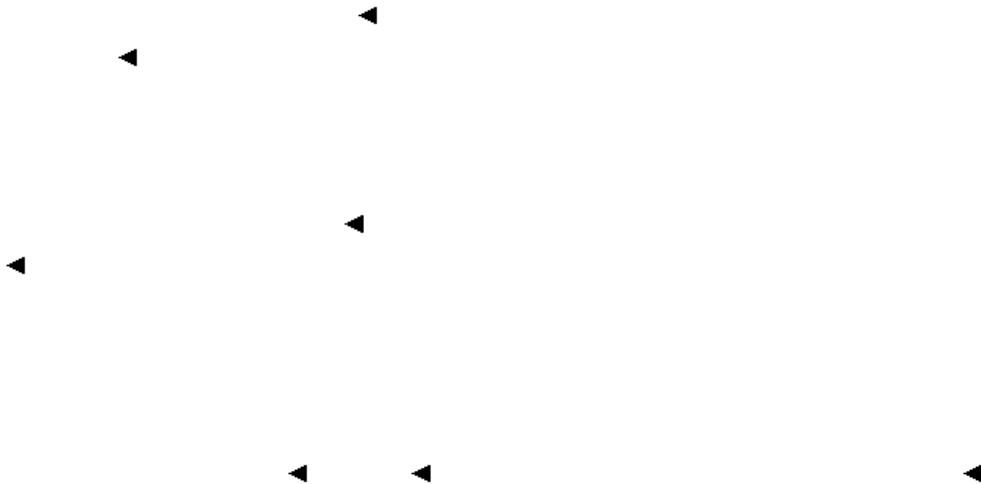
1

如右图所示：

程序第1段和第2段有三个参数生成：即为R01,T01,C01




2



3

4-1

13-1

A	B	C	D	E	F	G	H	I	J	K	L	M
<i>A</i>	<i>b</i>	<i>C</i>	<i>d</i>	<i>E</i>	<i>F</i>	<i>G</i>	<i>H</i>	<i>I</i>	<i>J</i>	<i>K</i>	<i>L</i>	
N	O	P	Q	R	S	t	U	Y	T			
<i>n</i>	<i>o</i>	<i>P</i>	<i>q</i>	<i>r</i>	<i>S</i>	<i>t</i>	<i>u</i>	<i>Y</i>	<i>T</i>			

1

PC PLC RS485 RS232 255

2

1 1200 2400 4800 9600 1 8 1

2

1

	(03)		0001	CRC16
010310010001D10A				
01	03	1001()0001	0001 D10A CRC CRC
www.tempinst.com				

2

		2		CRC16
0103027FFFD834				
01	03	02(2)7FFF	D834 CRC
7FFF	10	32767		

3

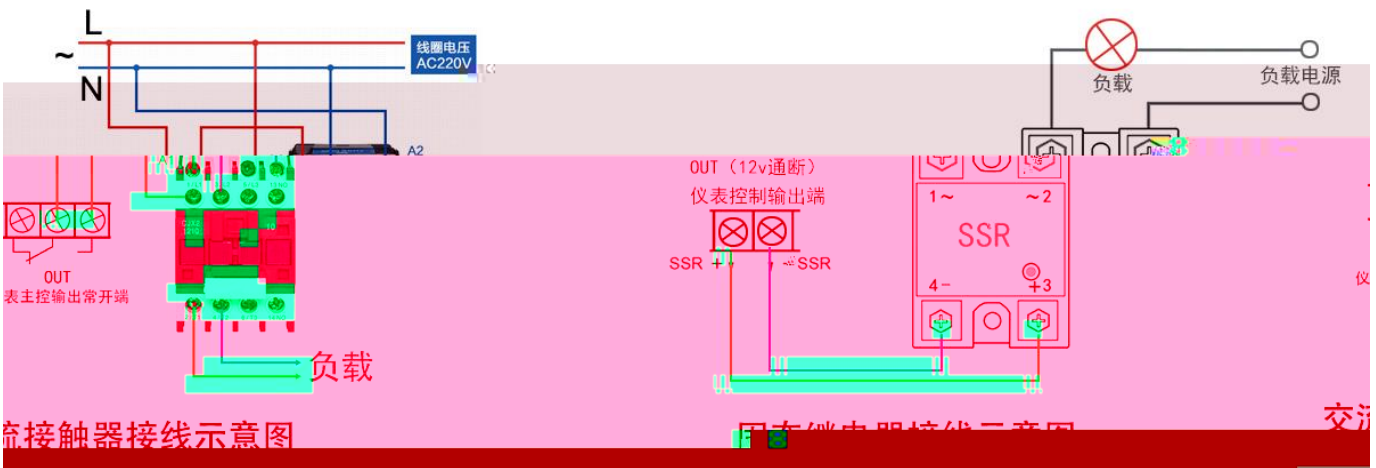
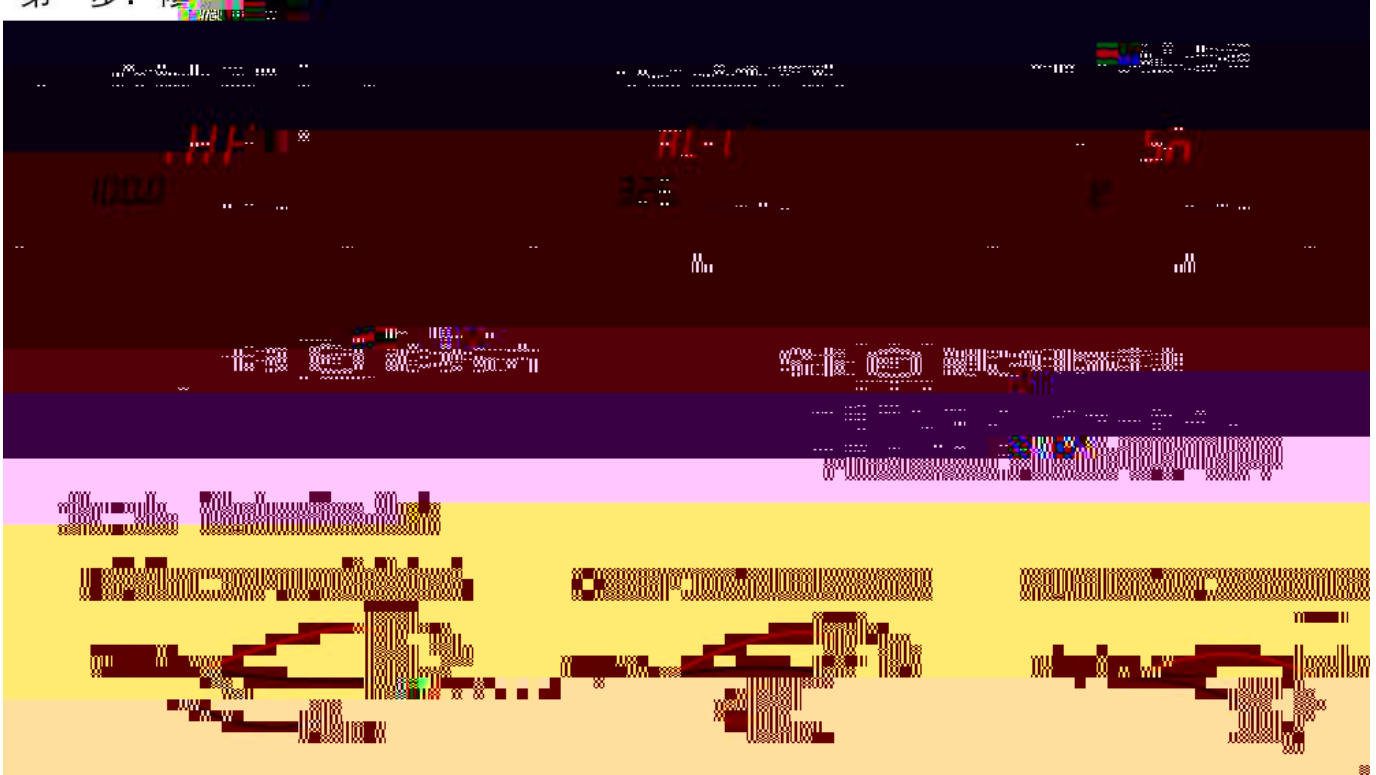
126

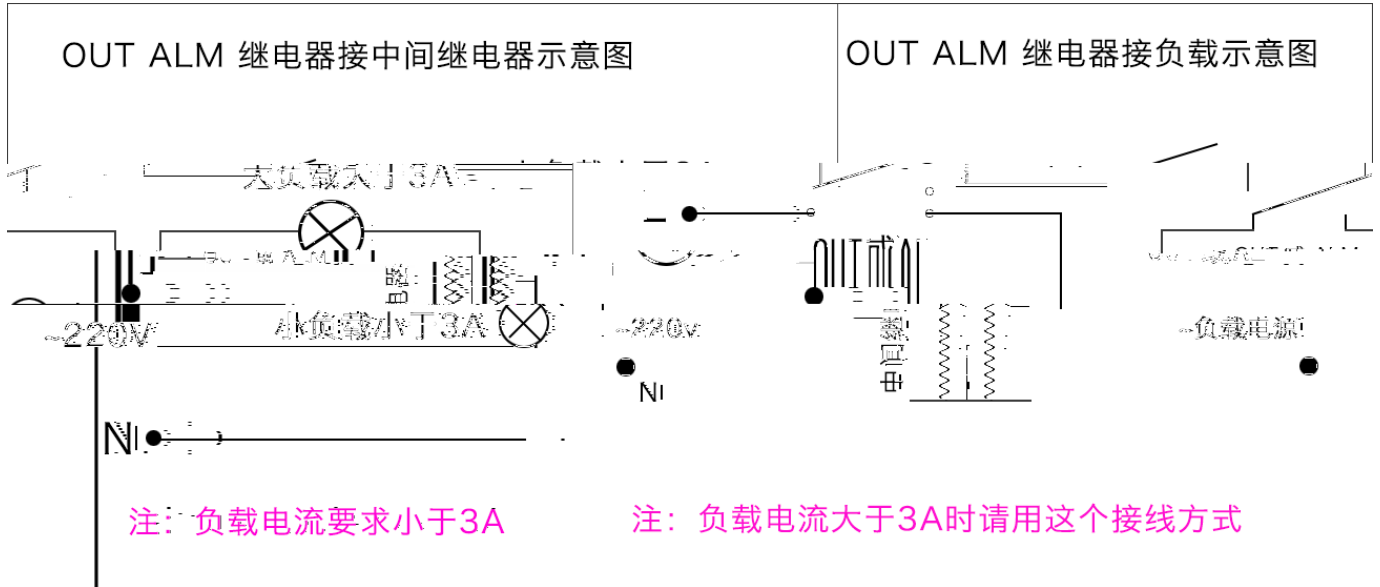
	(06)	00xx		CRC16
0106000004EC8A87				
01	06	0000()04EC	8A87 CRC
04EC	10	1260	10	12.5 125

(4-1)			
SP	YES	0000H	40001
AL-1	YES	0001H	40002
.....			
C32	YES	007FH	40128



第一步：修改仪表输入类型





	PID							
	KC	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
	160x80mm	:152x76mm()	M					
	80x160mm	:76x152mm()	MS					
	96x96mm	:92x92mm	MA					
	96x48mm	:92x44mm()	MF					
	48x96mm	:44x92mm()	ME					
	72x72mm	:68x68mm	MD					
	48x48mm	:44x44mm	MG					
	88x107x59mm DIN35		MR					
	PID		9P					
	1			1				
	2	(2)		2				
		: K, E, J, R, S, T, WR25, N				W		
		0-12v					<input type="checkbox"/>	
		4-20mA 0-10v					G	
							A	
		100 - 240V AC					<input type="checkbox"/>	
		24V DC					1	
		RS-485(MODBUS-RTU)						RS
		RS-232(MODBUS-RTU)						RX
		4-20mA						BS

